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## Ocean Optics Protocols For Satellite Ocean Color Sensor Validation, Revision 4, Volume III:

### Radiometric Measurements and Data Analysis Protocols

James L. Mueller, CHORS, San Diego State University, San Diego, California Giulietta S. Fargion, Science Applications International Corporation, Beltsville, Maryland Charles R. McClain, Goddard Space Flight Center, Greenbelt, Maryland

J. L. Mueller

CHORS, San Diego State University, San Diego, California

Andre Morel

Laboratoire d'Oceanographie, Universite Pierre et Marie Curie, Villefranche-sur-Mer, France Robert Frouin

Scripps Institution of Oceanography, University of California, San Diego, California

Curtiss Davis

Naval Research Laboratory, Washington, District of Columbia

Robert Arnone

Naval Research Laboratory, Stennis Space Center, Mississippi

Kendall Carder, Z.P. Lee, and R.G. Steward

University of South Florida, St. Petersburg, Florida

Stanford Hooker and Brent Holben

NASA Goddard Space Flight Center, Greenbelt, Maryland

Curtis D. Mobley

Sequoia Scientific Inc., Redmond, Washington

Scott McLean

Satlantic Inc., Halifax, Nova Scotia, Canada

Mark Miller

Department of Applied Science, Brookhaven National Laboratory, Upton, New York

Christophe Pietras and Giulietta S. Fargion

SAIC General Sciences Corporation, Beltsville, Maryland

Kirk D. Knobelspiesse

Science Systems and Applications, Inc., Greenbelt Maryland

John Porter

School of Ocean & Earth Science & Technology, University of Hawaii, Hawaii

Ken Voss

Physics Department, University of Miami, Florida

National Aeronautical and Space administration

**Goddard Space Flight Space Center** 

Greenbelt, Maryland 20771

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## Chapter 3

# **Above-Water Radiance and Remote Sensing Reflectance Measurement and Analysis Protocols**

James L. Mueller<sup>1</sup>, Curtiss Davis<sup>2</sup>, Robert Arnone<sup>3</sup>, Robert Frouin<sup>4</sup>, Kendall Carder<sup>5</sup>, Z.P. Lee<sup>5</sup>, R.G. Steward<sup>5</sup>, Stanford Hooker<sup>6</sup>, Curtis D. Mobley<sup>7</sup> and Scott McLean<sup>8</sup>

<sup>1</sup>Center for Hydro-Optics and Remote Sensing, San Diego State University, California

<sup>2</sup>Naval Research Laboratory, Washington, District of Columbia

<sup>3</sup>Naval Research Laboratory, Stennis Space Center, Mississippi

<sup>4</sup>Scripps Institution of Oceanography, University of California, San Diego, California

<sup>5</sup>University of South Florida, St. Petersburg, Florida

<sup>6</sup>NASA, Goddard Space Flight Center, Greenbelt, Maryland

<sup>7</sup>Sequoia Scientific Inc., Redmond, Washington

<sup>8</sup>Satlantic Inc., Halifax, Nova Scotia, Canada

#### 3.1 INTRODUCTION

As an alternative to the in-water methods of Volume III, Chapter 2, water-leaving radiance can be measured from the deck of a ship. A shipboard radiometer is used to measure radiance  $L_{\rm sfe}\left(\lambda,\theta,\phi\in\Omega_{\rm FOV};\theta_{\rm o}\right)$  emanating from the sea surface at zenith angle  $\theta$  (usually chosen between  $30^{\rm o}$  and  $50^{\rm o}$ ) and azimuth angle  $\phi$  (usually chosen between  $90^{\rm o}$  and  $180^{\rm o}$  away the sun's azimuth  $\phi_{\rm o}$ ). In the convention used here, azimuth angles  $\phi$  are measured relative to the sun's azimuth, i.e.  $\phi_{\rm o}=0$ .

The surface radiance measured with a radiometer having a solid-angle field of view (FOV) of  $\Omega_{FOV}$  sr may be expressed, following Mobley (1999), as

$$L_{\rm sfc}\left(\lambda,\theta,\phi\in\Omega_{\rm FOV};\theta_{\rm o}\right) = L_{\rm W}\left(\lambda,\theta,\phi\in\Omega_{\rm FOV};\theta_{\rm o}\right) + \rho L_{\rm sky}\left(\lambda,\theta_{\rm sky},\phi_{\rm sky}\in\Omega_{\rm FOV}';\theta_{\rm o}\right). \tag{3.1}$$

 $L_{\rm W}\left(\lambda,\theta,\phi\in\Omega_{\rm FOV};\theta_{\rm o}\right)$  is water-leaving radiance centered at angles  $(\theta,\phi)$  and averaged over  $\Omega_{\rm FOV}$  [as weighted by the radiometer's directional response function (see Volume II, Chapters 2 and 3)].  $L_{\rm sky}\left(\lambda,\theta_{\rm sky},\phi_{\rm sky}\in\Omega'_{\rm FOV};\theta_{\rm o}\right)$  is sky radiance measured with the radiometer looking upward at angles  $(\theta_{\rm sky},\phi_{\rm sky})$ . In practice,  $\theta$  and  $\theta_{\rm sky}$  are numerically equal angles in the nadir and zenith directions, respectively, and the sea and sky viewing azimuths  $\phi=\phi_{\rm sky}$ . The reflectance factor  $\rho$  is operationally defined as the total skylight actually reflected from the waveroughened sea surface into direction  $(\theta,\phi)$  divided by sky radiance measured with the radiometer from direction  $(\theta_{\rm sky},\phi_{\rm sky})$ , both quantities being averaged over  $\Omega_{\rm FOV}$  (Mobley 1999). Remote sensing reflectance is then determined, using water-leaving radiance calculated from (3.1), as

$$R_{\text{RS}}(\lambda, \theta, \phi \in \Omega_{\text{FOV}}; \theta_o) = \frac{L_{\text{W}}(\lambda, \theta, \phi \in \Omega_{\text{FOV}}; \theta_o)}{E_{\text{S}}(\lambda; \theta_o)}, \tag{3.2}$$

where  $E_S(\lambda;\theta_0)$  is incident spectral irradiance measured above the sea surface. All of the above variables vary with solar zenith angle  $\theta_0$ .

A simplified notation is used in Volume III, Chapter 2 (and elsewhere in the protocols) when discussing water leaving radiance  $L_{\rm W}(\lambda)$  and remote sensing reflectance  $R_{\rm RS}(\lambda)$  derived from in-water profile measurements of  $L_{\rm U}(z,\lambda)$ . Because  $L_{\rm U}(z,\lambda)$  is measured in water viewing the nadir direction,  $L_{\rm W}(\lambda)$  represents radiance leaving the surface in the zenith direction  $(\theta,\phi)=(0^{\rm o},0^{\rm o})$ . Therefore,  $L_{\rm W}(\lambda)$  in, e.g., Volume III, Chapter 2 corresponds to  $L_{\rm W}(\lambda,0,0\in\Omega_{\rm FOV};\theta_{\rm o})$ , and  $R_{\rm RS}(\lambda)$  to  $R_{\rm RS}(\lambda,0,0\in\Omega_{\rm FOV};\theta_{\rm o})$ , in the present notation .